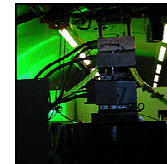
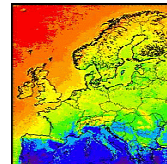
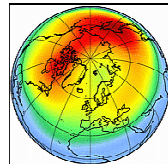


Predictability

George Craig
and the internet

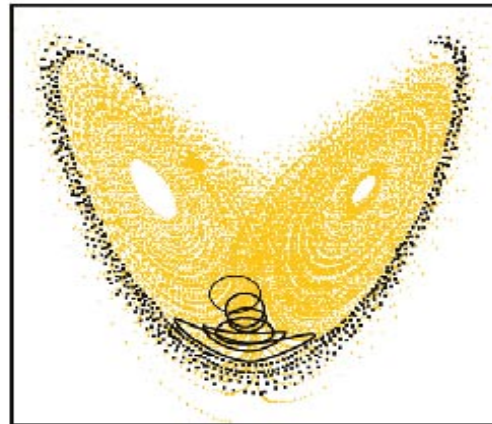


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Chaos and (Un)predictability

Sensitive
dependence
on initial
conditions
(sometimes)



$$\frac{dX}{dt} = F[X] \text{ is a nonlinear system}$$

$$\Rightarrow \frac{d \delta X}{dt} = \frac{dF}{dX} \delta X \equiv J \delta X$$

Since F is a nonlinear function of X

$$\Rightarrow J = J(X)$$

\Rightarrow Finite time predictability

depends on starting conditions

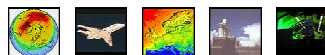
9 September 2002

ECMWF Seminar



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Palmer, 2002

Error Growth in Convection

Consider an idealised field of convective clouds
(Lean, Gray and Clark, 2004)

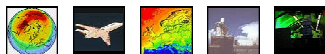
- Nonhydrostatic NWP model, 4km resolution
- unstable sounding with capping inversion
- Initial perturbations to boundary layer theta
- same perturbation field with +/- amplitude

How fast do the simulations diverge?



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Perturbations

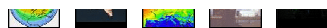
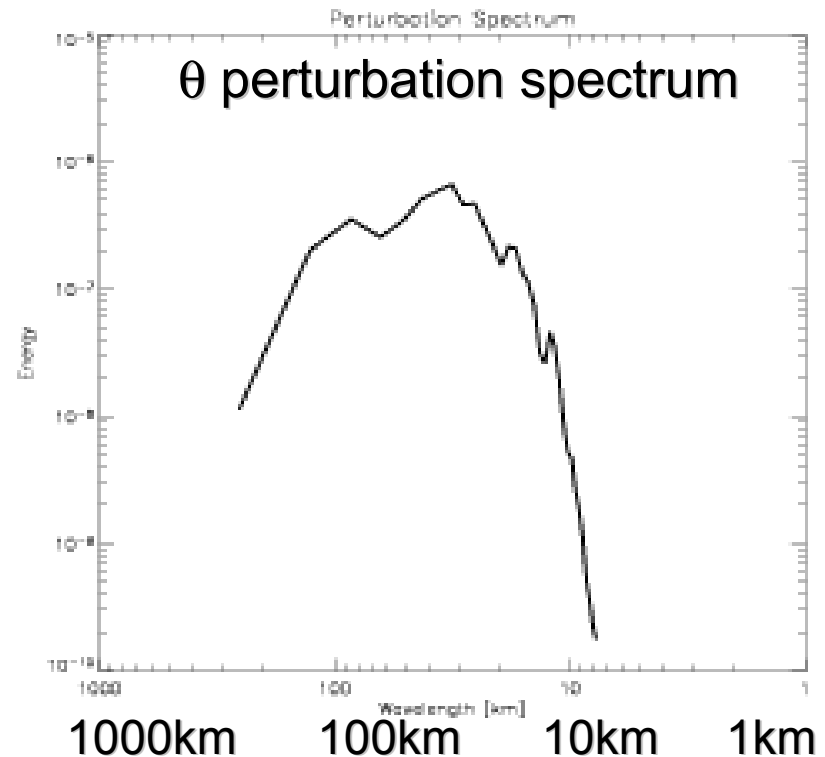
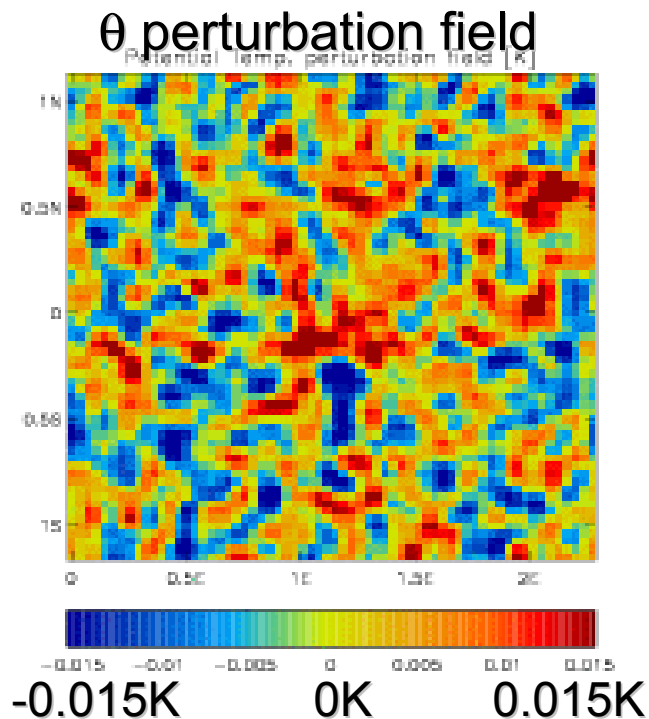
Random Gaussian Kernals

- Spatially coherent
- Allow user to specify spatial scale

Lean, Gray and

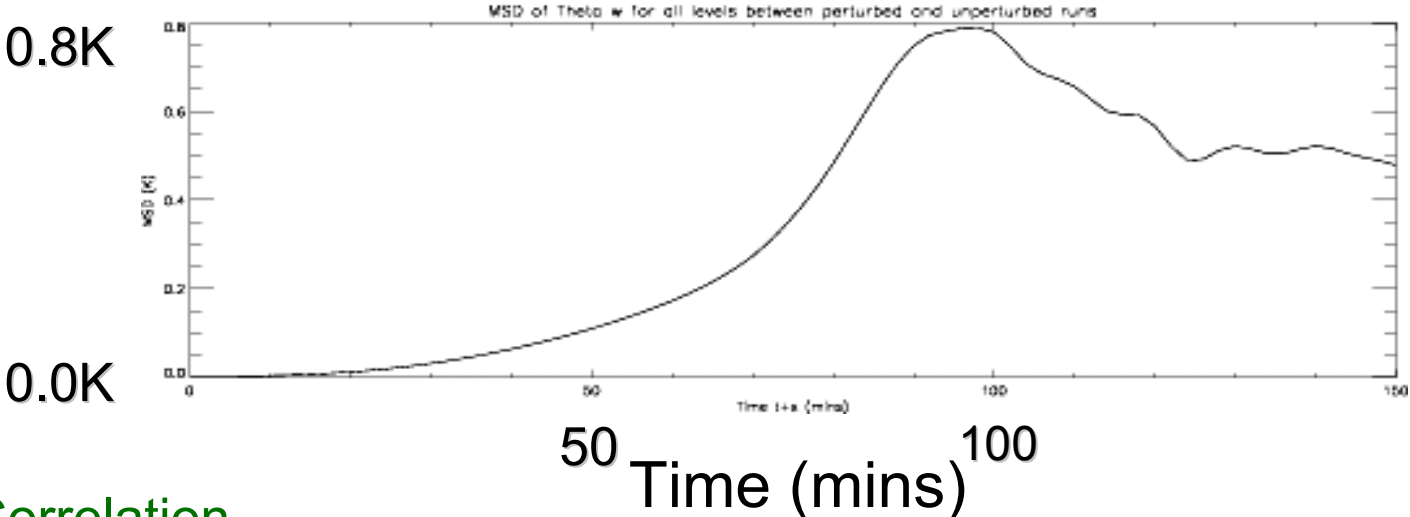
Clark, 2004

Added to the θ field at the Lifting Condensation Level.

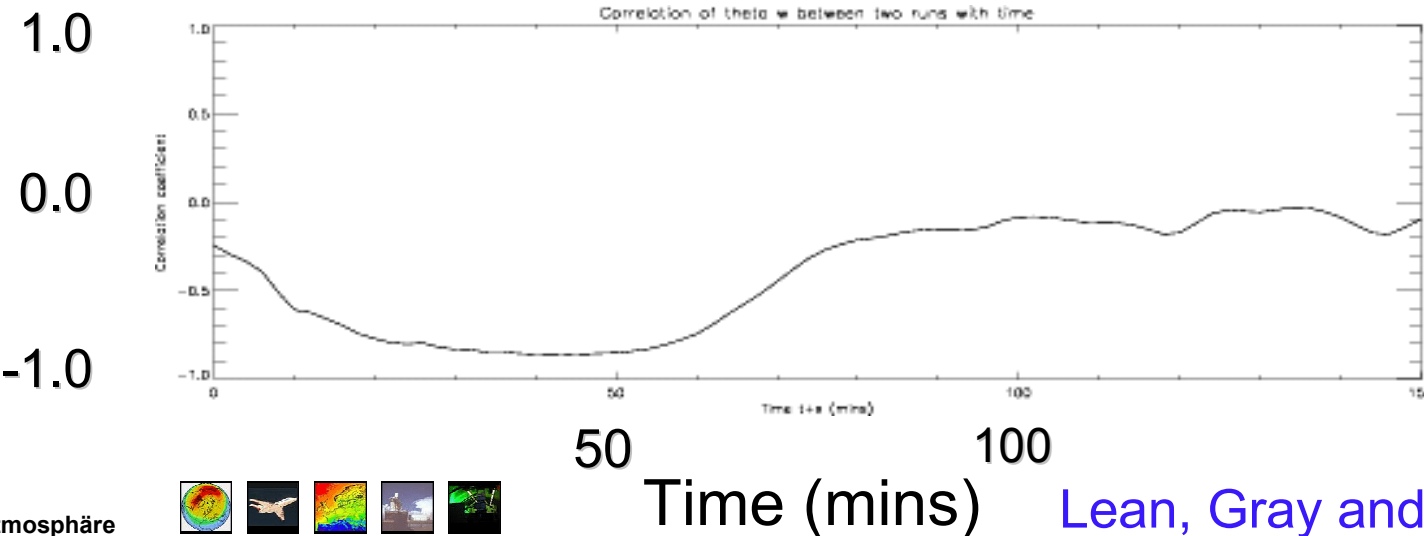


Growth of perturbations

- Mean Square Difference



- Correlation



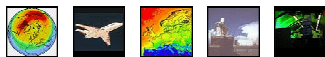
IHOP 2002

Importance of Mesoscale Structure

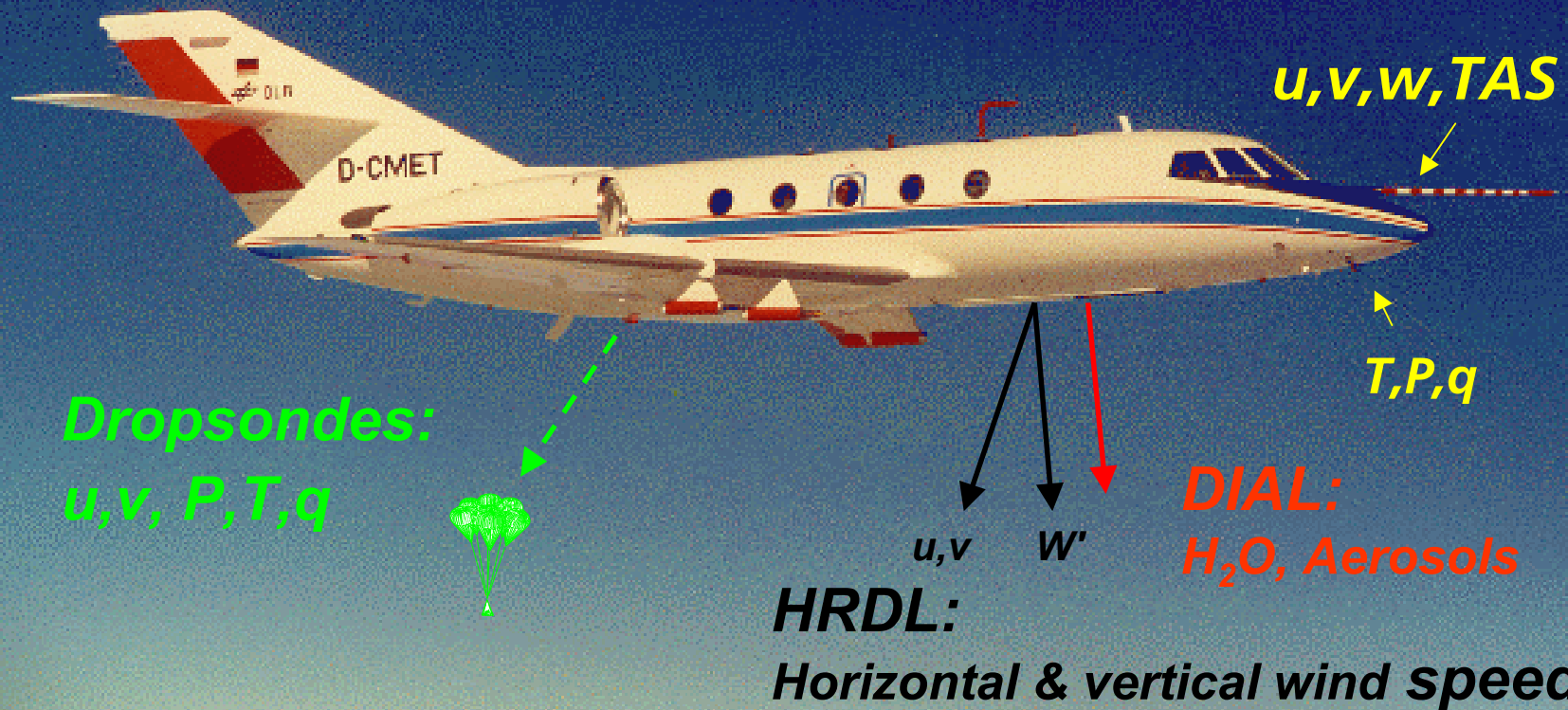


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Falcon payload during IHOP_2002

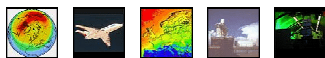


Kiemle, Ehret, Fix, Flentje, Poberaj, Wirth, Hardesty, Brewer and Sandberg, 2004



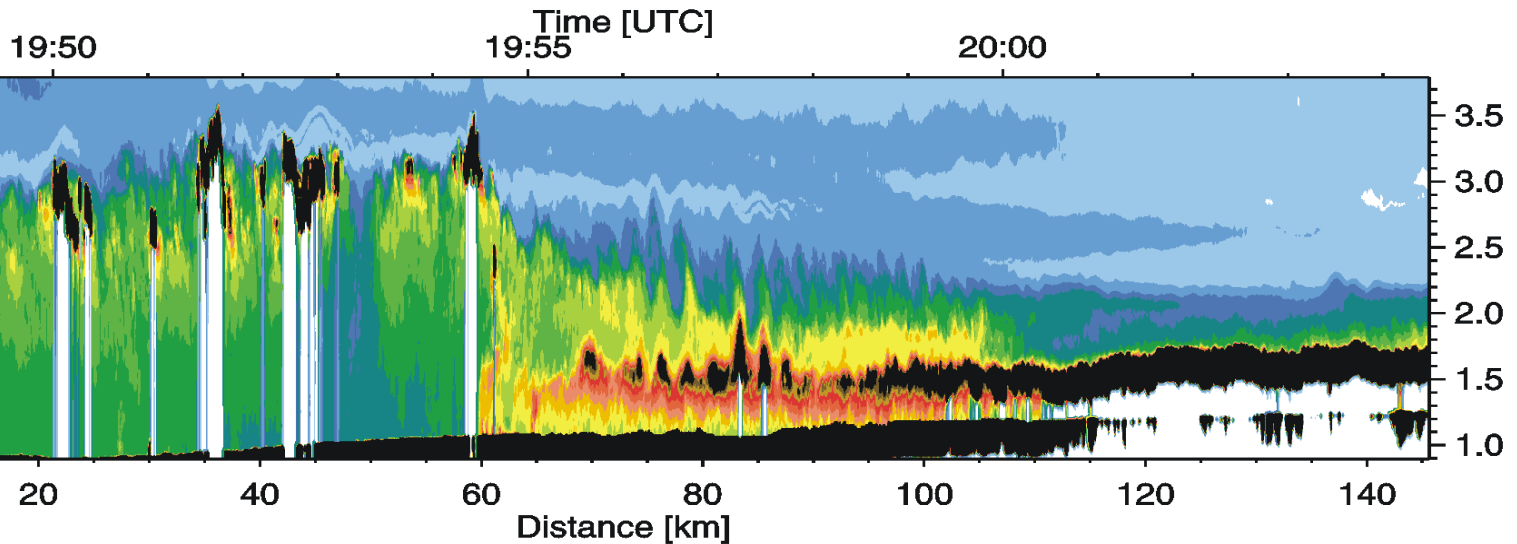
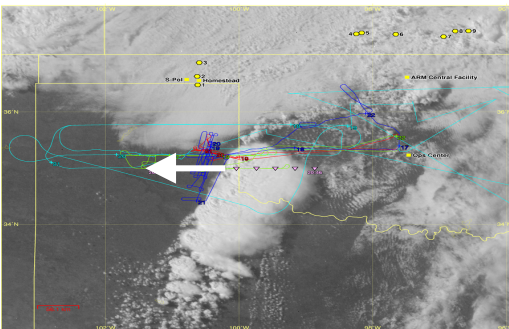
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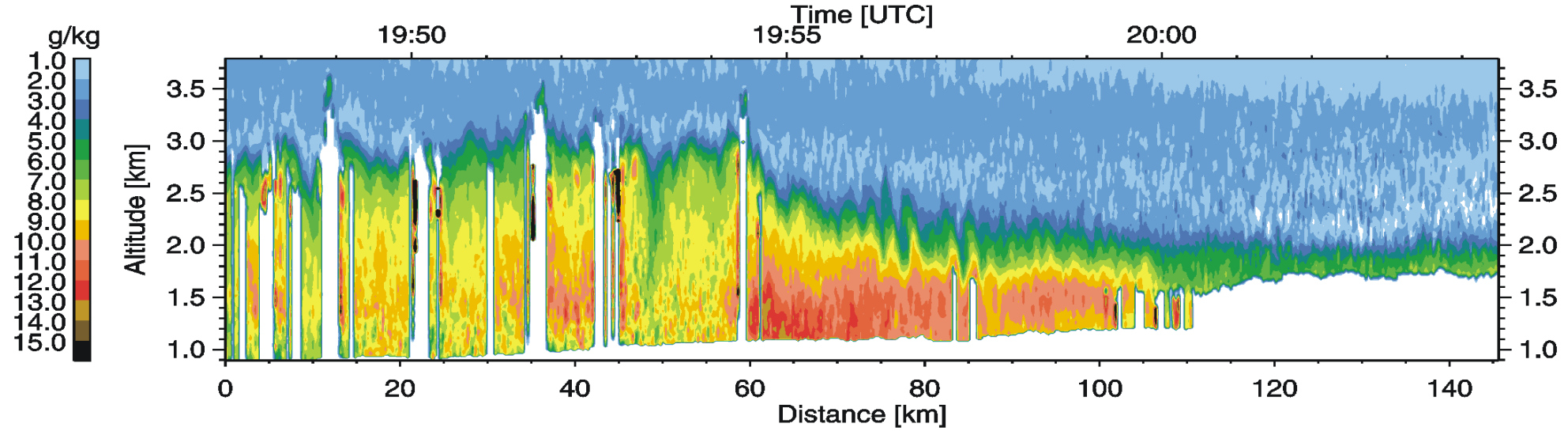


IHOP 24 May 2002 Leg3a Backscatter Intensity at 1064nm

Kiemle et al., 2004



Water Vapor Mixing Ratio



Lat	35.23	35.23	35.23	35.23	35.23	35.23	35.23	35.23	35.23
Lon	-100.01	-100.19	-100.37	-100.54	-100.72	-100.89	-101.06	-101.24	-101.41

Example: Boundary Evolution

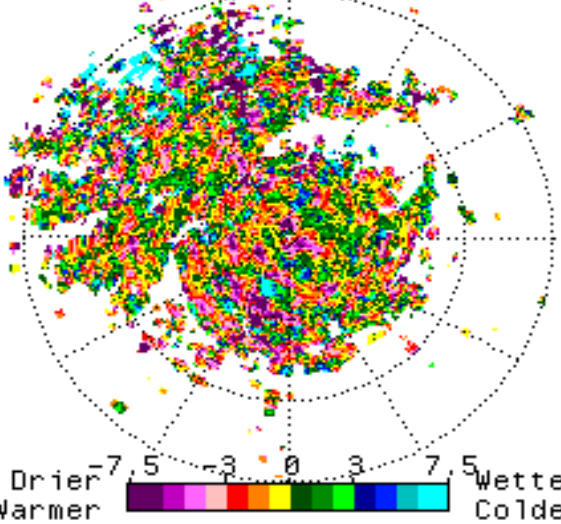
Fabry, 2004

FROM SURFACE OBSERVATIONS

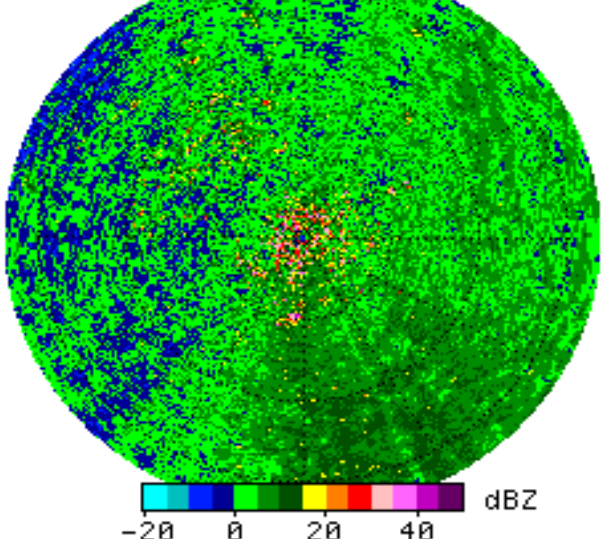
2031Z: P= 905.0 T=+31.7 Td=+6.8
 2036Z: P= 904.9 T=+31.8 Td=+6.1

Theory: $N = 77.6 P/T + 373000 e/T^2$
 Density term Wet term
 2036Z: 230.0 ± 0.6 37.7 ± 9.0
 1-scan change: -0.1 -1.8
 Expected N at 2036Z: 267.7 ± 9.0
 Observed N at 2036Z: $265.2 -0.73$

1-SCAN REFRACTIVITY CHANGE

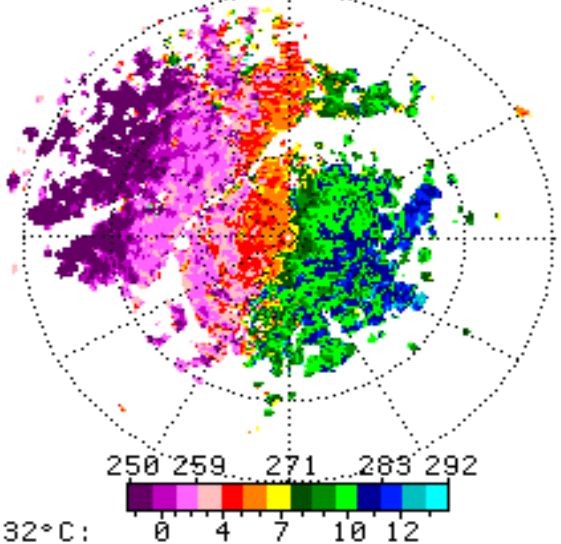


REFLECTIVITY

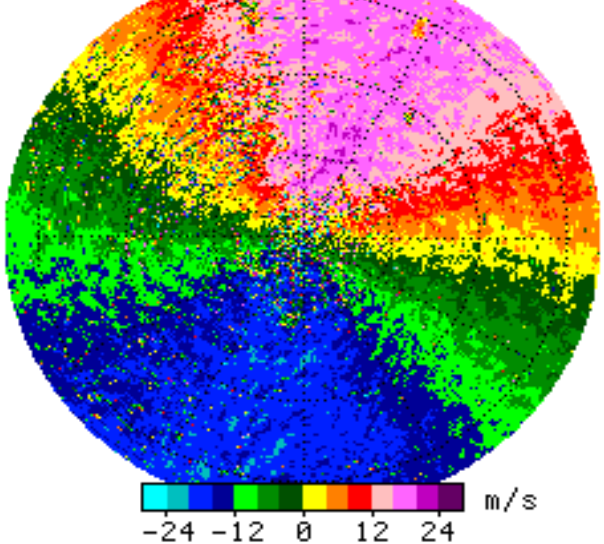


22-MAY-2002 20:36Z

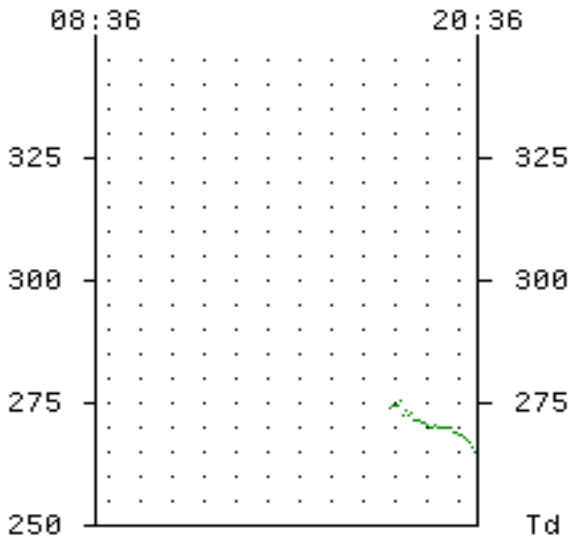
CURRENT REFRACTIVITY MAP



VELOCITY



12-HR HISTORY OF MEAN N



Td at 32°C:

0 4 7 10 12

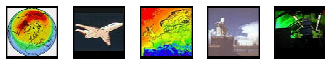
MAP

Importance of Orography



DLR

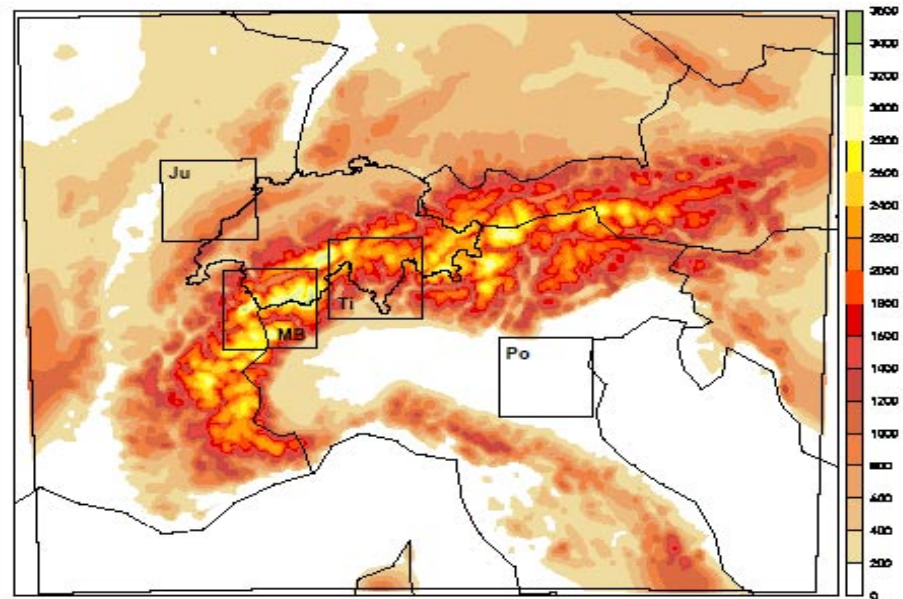
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Ensemble Simulation (6 members)

The MC2 Model

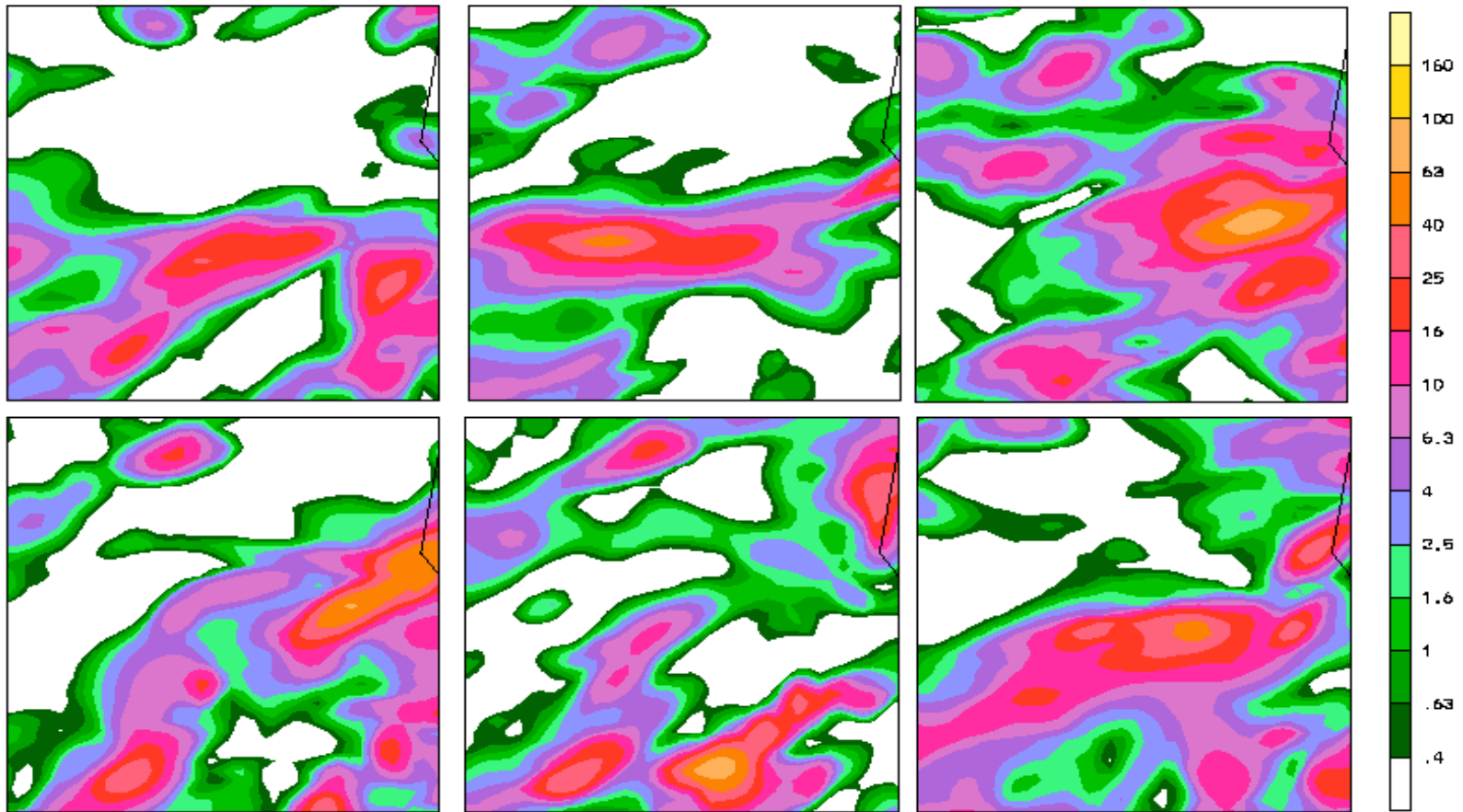
- 3 km horizontal grid-spacing
- 50 vertical levels
- 1030 x 880 km domain over the European Alps
- non-hydrostatic
- semi-lagrangian and semi-implicit
- convection treated explicitly (no parameterization)
- surface scheme: simplified force-restore method.



Walser, Lüthi and Schär, 2004

Flat terrain

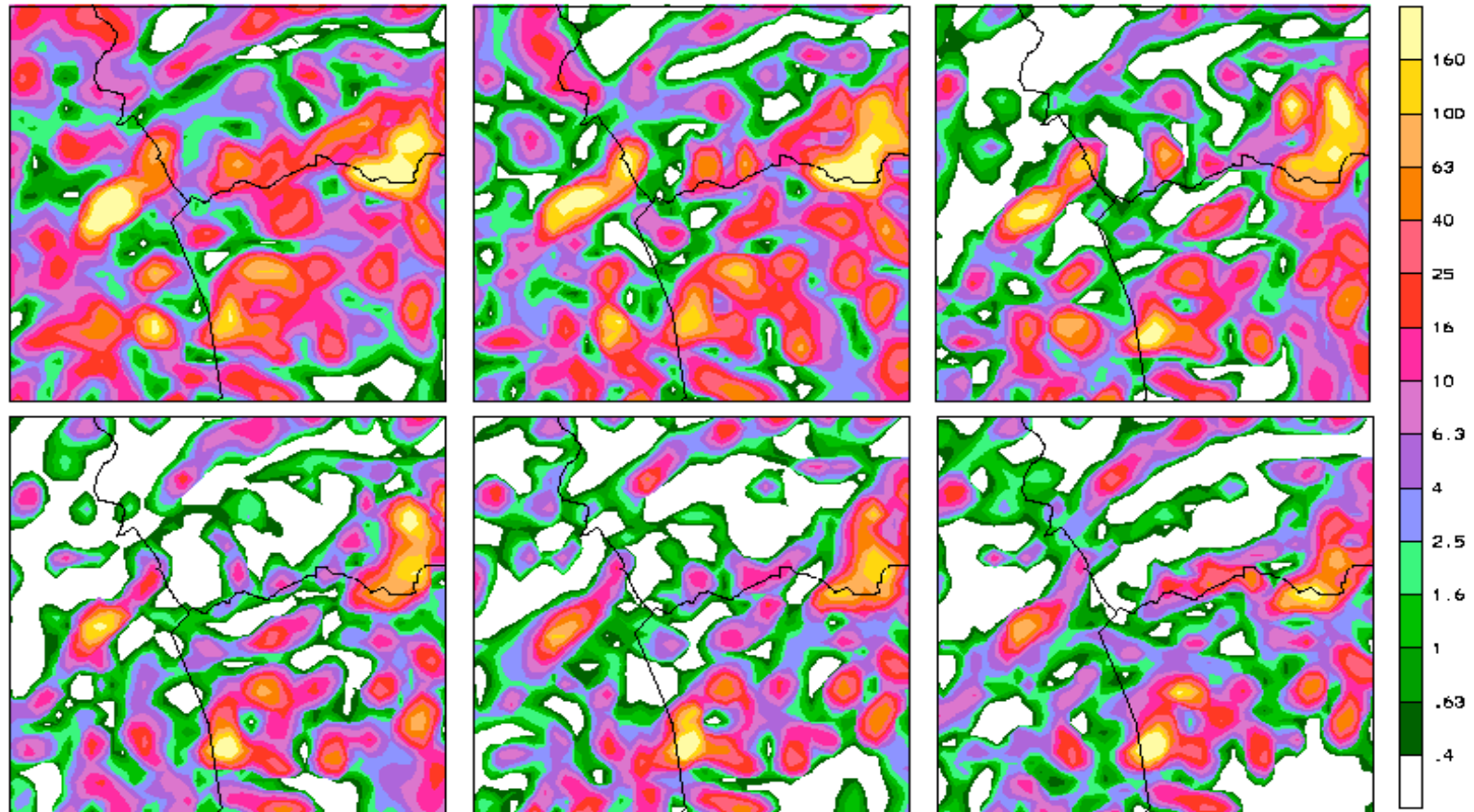
29 July 1999 subdomain Po: thermal convection



Daily precipitation sum [mm] for members 1-6

Alpine region

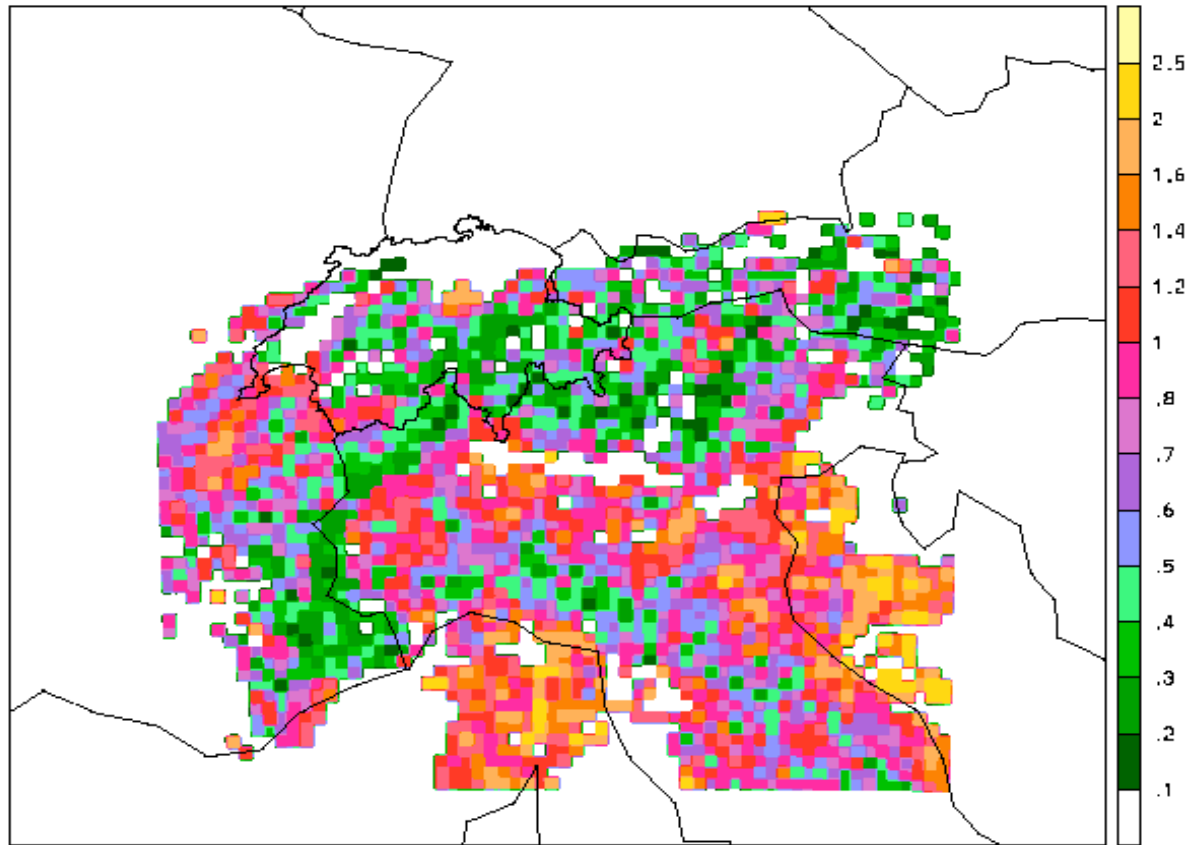
29 July 1999 subdomain Mont Blanc: thermal convection



Daily precipitation sum [mm] for members 1-6.

Variability of Precipitation in Ensemble

29 July 1999: Geographical variability of predictability



Ratio of standard deviation to the ensemble mean (threshold 1mm) of daily precipitation.

COPS

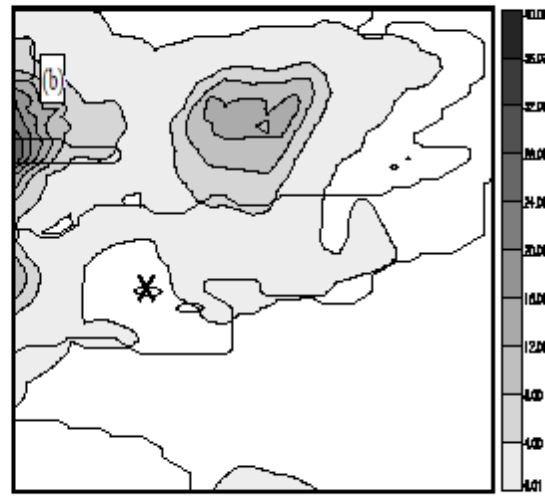
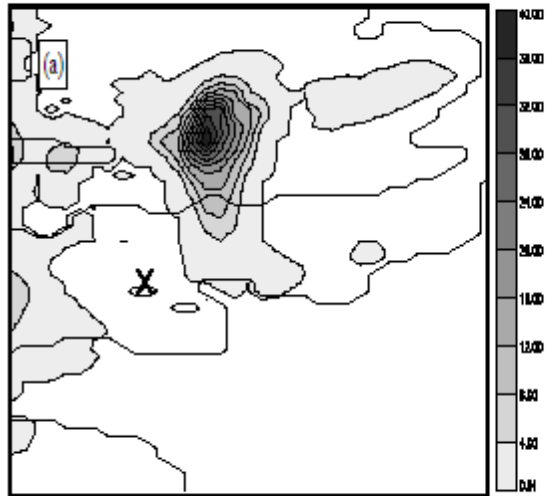
What determines extent of convective predictability
in intermediate orography?

Different Kinds of Predictability

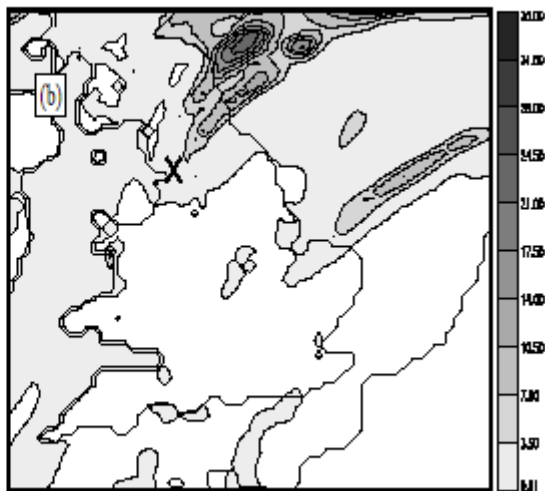
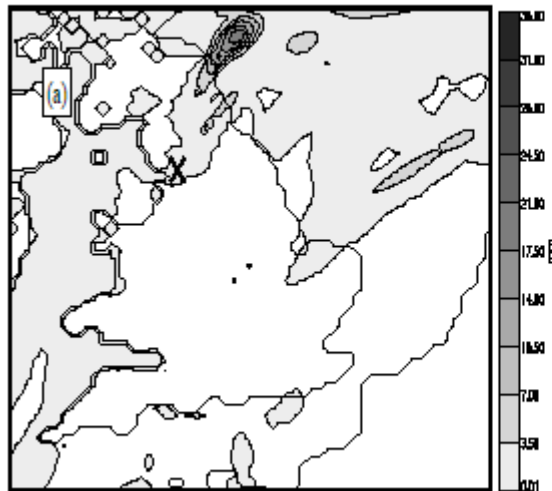
Deterministic Forecast

Ensemble Mean (6 mem)

6 hour accumulated
precipitation



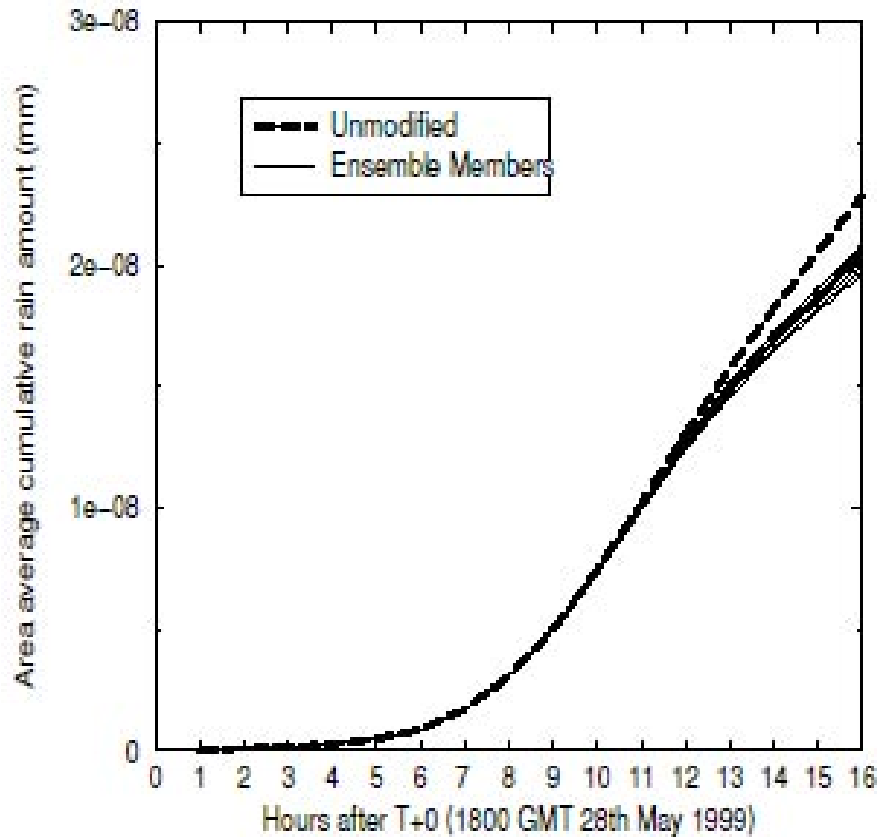
Elevated warm front
No CIN
Location unpredictable



Moderate orography
Moderate CIN
Location predictable

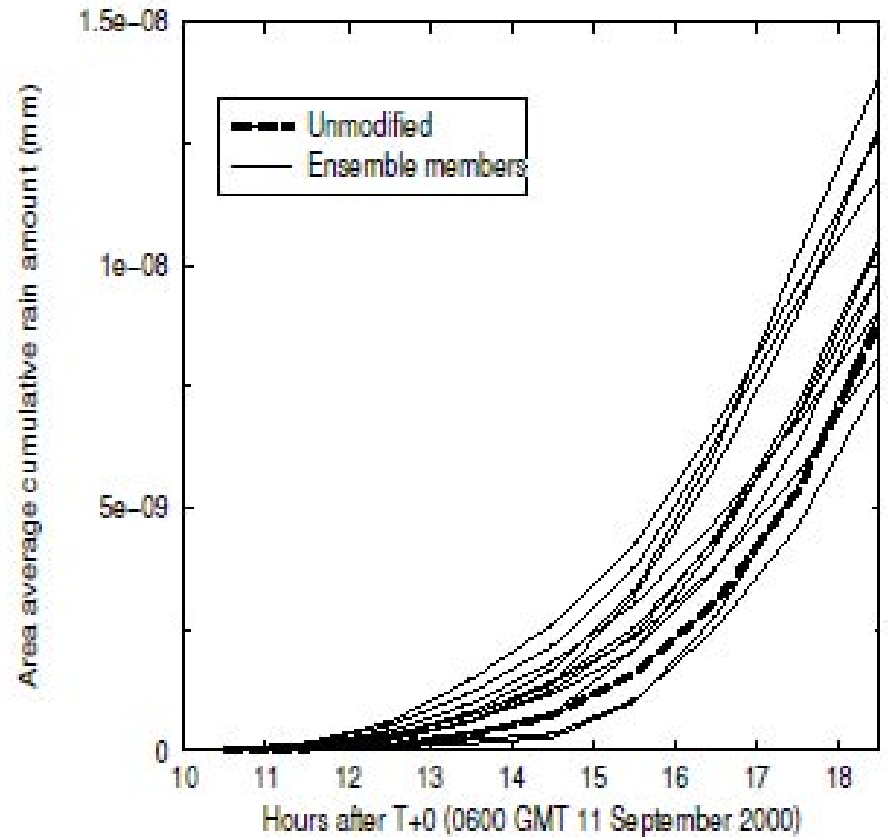
Done, Craig, Gray,
Clark and Gray, 2005

Elevated warm front
No CIN



Location *unpredictable*
Amount predictable

Moderate orography
Moderate CIN



Location predictable
Amount *unpredictable*

Conclusions

- User requirements can not always be satisfied.
But we can do better, especially probabilistic info
- MAP - in strong orography, it may be enough to know the synoptic flow
- IHOP - small-scale triggers can often be observed
- For moderate orography, need to predict three things:
 1. orography
 2. synoptic environment
 3. mesoscale structure

Conclusions

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